PBO GPS Station Position Time Series Naming Convention and Format Description Version 1.0.1

This document describes the naming convention and internal format for PBO GPS time series files, version 1.0.1.

1 Background

PBO has two GPS Analysis Centers (ACs) that process raw GPS data and produce position solutions for all stations in the PBO and PBO Nucleus networks as well as selected other stations One AC is operated by the Geodesy Laboratory at Central Washington University and the other by the Berkeley Seismological Laboratory at the University of California, Berkeley. These ACs produce GPS station position solutions on a daily basis using rapid orbit products ("rapid" solutions), as well as with about 14 days latency using the final orbit products ("final" solutions). The ACs send both the rapid and final solutions to the PBO Analysis Center Coordinator (ACC) at MIT. The rapid and final products are available separately from the PBO GPS Archives with latencies of about 24 hours and 14 days, respectively.

The ACC first rotates each of the individual AC products into a single common reference frame. The ACC then combines these intermediate rotated products to produce a single best-estimate PBO combined solution for station position and velocity. The intermediate and final combined products are also available from the PBO GPS Archives with latencies of about 24 hours and 14 days (rapid and final).

For further details of the GPS processing and products, please see the PBO GPS Processing Plan and the Preliminary Design Review document for PBO data management, both of which are available on the PBO web site.

2 File Name Convention

Each of the time series products created by the GPS Analysis Center Coordinator is identified with a unique file name, with the structure

<STATION>.<AC_ID>.<PROD_ID>.pos

where

• <STATION>

4-character PBO Dot Number or 16-character PBO station name

• <AC_ID>

A string that identifies the PBO Analysis Center from whose work the time series is derived. Values are one of CWU (Central Washington University), BSL (Berkeley Seismological Laboratory), or PBO (Combined solution from MIT).

• <PROD_ID>

A string that identifies the product type. Values are rapid_frame: Rapid product from a given AC, rotated into a common reference frame.

final_frame: Final product from a given AC, rotated into a common reference frame. rerun_frame: Rerun product from a given AC, rotated into a common reference frame.

For example, the time series for station P041 derived from final solutions generated by Central Washington University, and in the standard PBO reference frame, would be named P041.CWU.final_loose.pos. The time series for station P511 derived from the final combined solution produced by MIT would be named P511.PBO.final_frame.pos.

3 PBO GPS Station Position Time Series Format

PBO GPS station position time series are made available in ASCII format. The file begins with a set of header lines as given in Table 1.

Line	Entry	Definition
1	PBO Station Position Time Series	
2	Format Version: 1.0.1	
3	4-character ID: SSSS	4-character PBO Dot Number
4	Station name: CCCCCCCCCCCCCCC	16-character station name
5	First epoch: YYYYMMDD HHMMSS	Date and time of first data point in the file, in UTC
6	Last epoch: YYYYMMDD HHMMSS	Date and time of last data point in the file, in UTC
7	Release date: YYYYMMDD HHMMSS	Date and time at which the time series file was re-
		leased, in UTC
8	XYZ reference position: X Y Z	Reference position of the station, in ITRF standard
		Cartesian coordinates with units of meters.
9	NEU reference position: N E U	Reference position of the station with respect to the
		WGS-84 standard ellipsoid. N is latitude in decimal
		degrees, with North positive. E is longitude in deci-
		mal degrees, with East positive. U is elevation with
		respect to the WGS-84 ellipsoid, in meters.

 Table 1: PBO GPS Station Position Time Series Header Format

Following the header are a series of lines giving position information as a function of time. Each line gives the position estimate at a particular epoch. These lines have the structure

YYYYMMDD HHMMSS JJJJJJ X Y Z xx yy zz xy xz yz N E U Ndel Edel Udel nn ee uu ne nu eu <quality>

The entries are described in Table 2 below. Note that all times and dates given are in UTC.

Entry	Definition	
ҮҮҮҮ	4-digit year for the given position epoch	
MM	2-digit month of year for the given position epoch	
DD	2-digit day of month for the given position epoch	
HH	2-digit hour for the given position epoch	
MM	2-digit minute for the given position epoch	
SS	2-digit second for the given position epoch	
JJJJJ	Modified Julian day for the given position epoch	
ХҮZ	ITRF Cartesian coordinates, meters	
xx	Standard deviation of the X position, meters	
уу	Standard deviation of the Y position, meters	
ZZ	Standard deviation of the Z position, meters	
xy	Correlation of the X and Y position	
xz	Correlation of the X and Z position	
yz	Correlation of the Y and Z position	
Ν	North latitude, decimal degrees, relative to WGS-84 ellipsoid	
Е	East longitude, decimal degrees, relative to WGS-84 ellipsoid	
U	Elevation, meters, relative to WGS-84 ellipsoid	
Ndel	Change in North component relative to NEU reference position, meters. If the	
	station moves northward, Ndel is positive.	
Edel	Change in East component relative to NEU reference position, meters. If the station	
	moves eastward, Ndel is positive.	
Udel	Change in vertical component relative to NEU reference position, meters. If the	
	station moves upward, Ndel is positive.	
nn	Standard deviation of Ndel, meters	
ee	Standard deviation of Edel, meters	
uu	Standard deviation of Udel, meters	
ne	Correlation of Ndel and Edel	
nu	Correlation of Ndel and Udel	
eu	Correlation of Edel and Udel	
<quality></quality>	'final' or 'rapid', corresponding to products generated from final or rapid orbit prod-	
	ucts	

 Table 2: PBO GPS Station Position Time Series Format

See the PBO web page for a reference for the Modified Julian date.

An example file derived from the Berkeley final solution rotated into the common PBO reference frame would be named P041.BSL.final_frame.pos and have the following internal structure

PBO Station Position Time Series Format Version: 1.0.1 4-character ID: P041 Station name: Marshall_CO2004 First epoch: 20040120 000000 Last epoch: 20050930 000000 Release date: 20051001 000000 XYZ reference position: -2382952.20260893 -3688233.91924966 4610508.43527586 NEU reference position: 39.949481 -105.193900 1809.6159 20040120 000000 53024.0 -2382952.20260893 -3688233.91924966 4610508.43527586... 0.01234 0.05678 0.09012 0.03456 0.07890 0.01234 ... 39.949481 -105.193900 1809.6159 0.00000 0.00000 0.00000 0.01234 0.05678... 0.09012 0.03456 0.07890 0.01234 final 20040121 000000 53025.0 -2382952.20260942 -3688233.91924927 4610508.43530291... 0.01234 0.05678 0.09012 0.03456 0.07890 0.01234 ... 39.949481 -105.193900 1809.6159 0.00000 0.00000 0.00000 0.01234 0.05678... 0.09012 0.03456 0.07890 0.01234 final

and so on, where ... indicates that a single line has been broken for clarity.